

Mechatronics Design – Class#15

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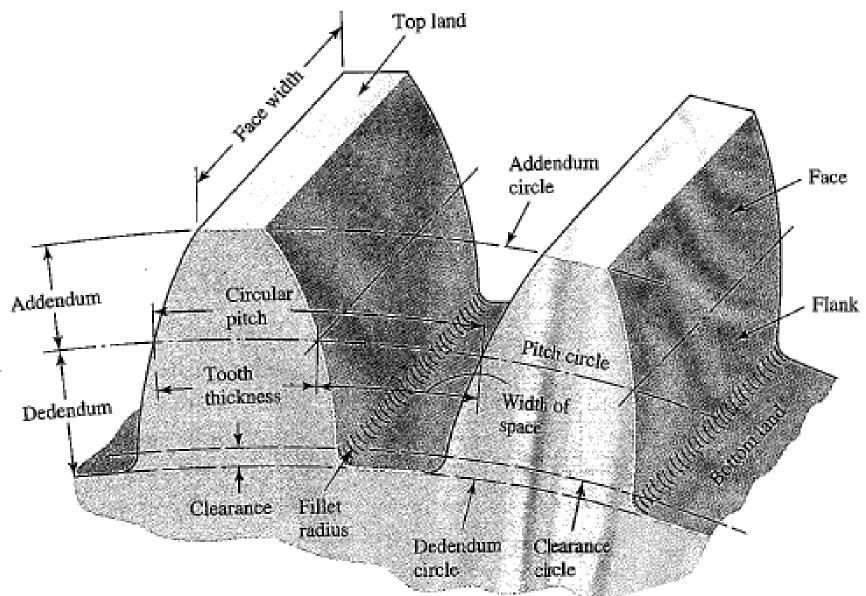


Outline

- **♦** Review
 - Gears fundamentals
- **♦** Involute
- ◆ Contact length & Contact Ratio
- ◆ HW#3 (due next Monday)



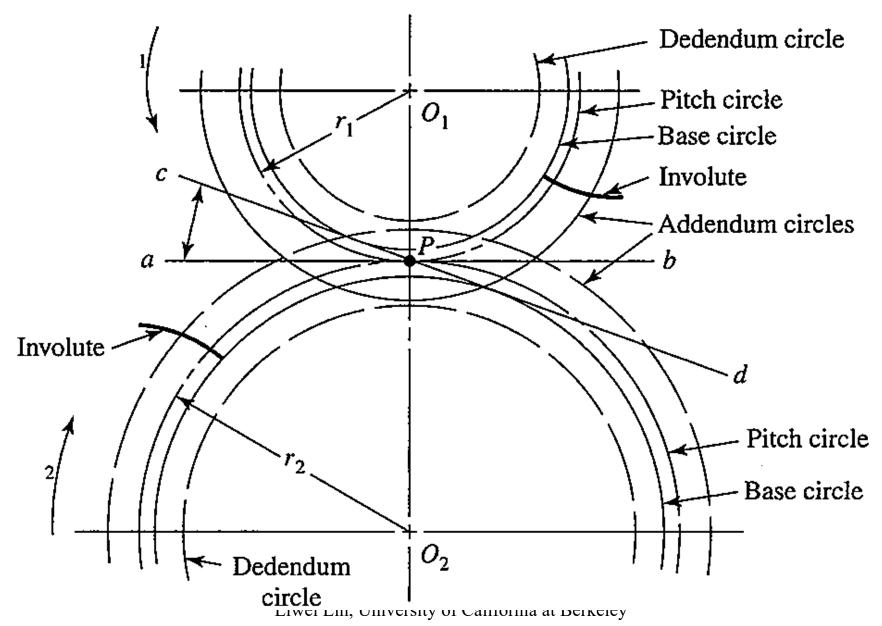
Gears



Liwei Lin, University of California at Berkeley



Gear Circles





Basic Numbers



Conjugate Action

When tooth profiles are designed to produce a constant angular velocity ratio during meshing

In theory, given one tooth profile, one can fine the profile for meshing tooth for conjugate action

One solution is involute profile - universal use for gears



Graphic Explanation

(is the contact point where two surfaces are trangent to each other if Pis not changing 0 & 0' do not teel the change (no matter what the shapes one) constant angular velocity



Line of Action

force is acting on normal ab

me of action pressure true

Pis the intersection point

of ab \$ 00'

pitch point

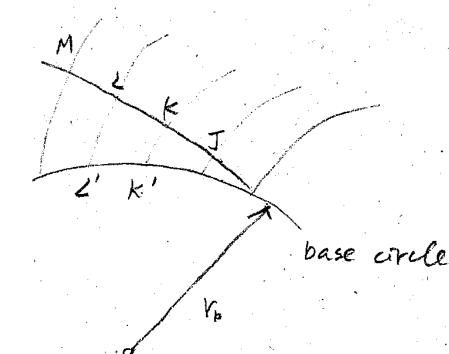


Involute

lows traced by the free end

of a taut string that is "unwrapped"

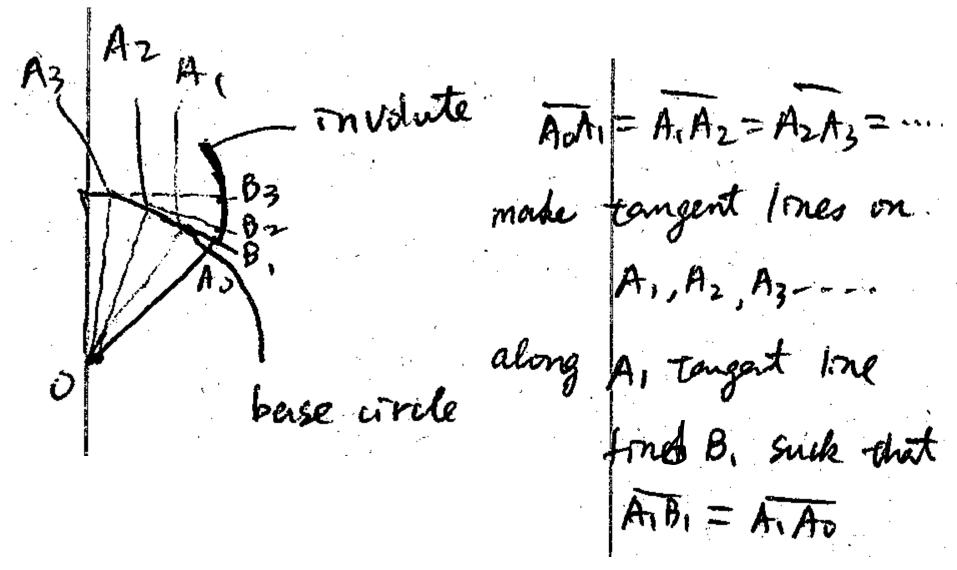
from the circle



taut string property



Making Involute Profile



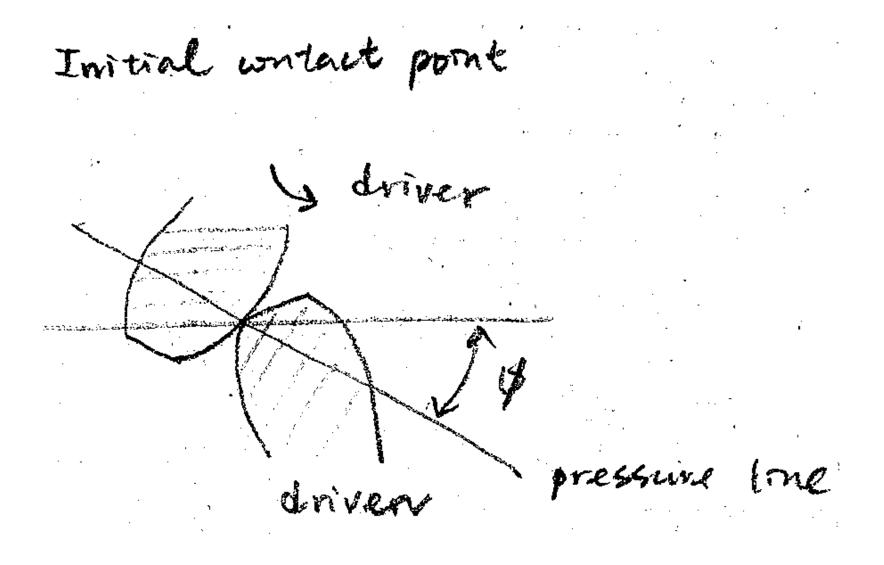


Pressure Line

-) always tangent to base circles normal to the mobile at point of Saristy the requirement messure line



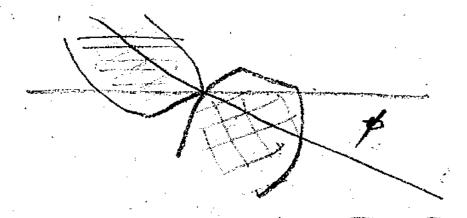
Initial Contact





Final Contact

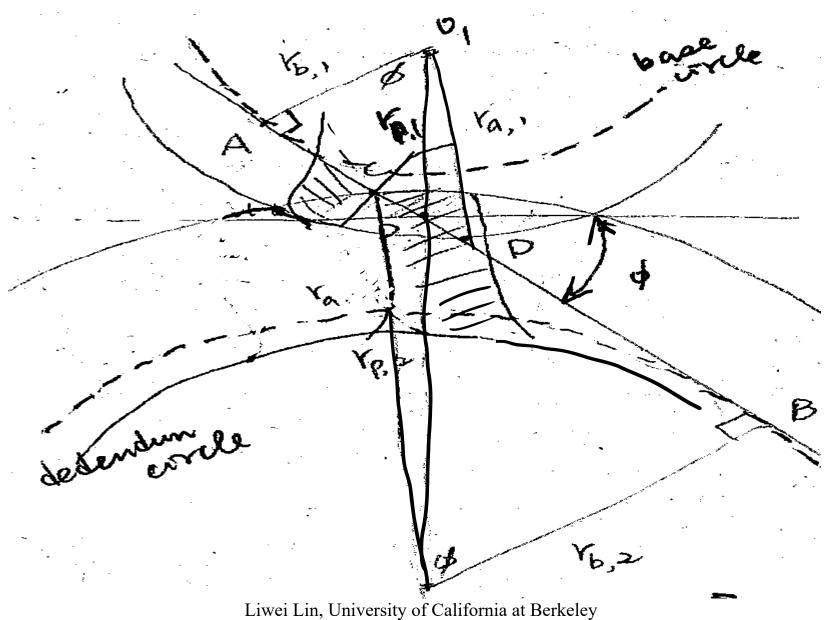
final contact



contact starts when addendum circle of driver gear merculo the pressure line ends when addendum circle of driver gear mersects the pressure line

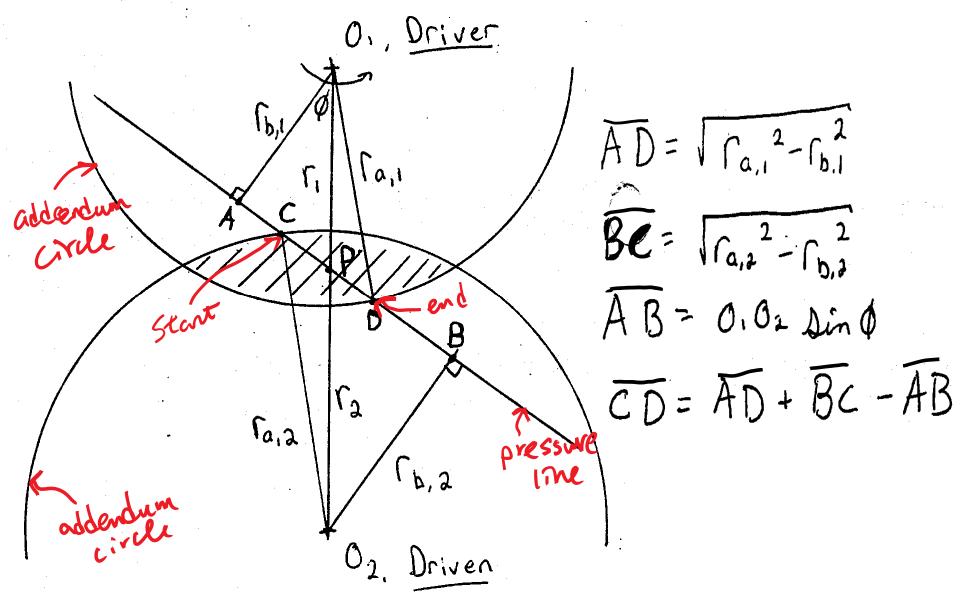


Contact - Graphics





More Clean Figure





Contact Ratio

- A+B are pts of tangency to bose circles

where
$$\frac{\Gamma_b}{N} = \frac{\Gamma_{b,1}}{N_1} = \frac{\Gamma_{b,2}}{N_2}$$

In general:



Detailed Numbers

$$\overline{AD} = \sqrt{8a^2 - 7b^2}$$

$$BC = \sqrt{6a^2 - 7b^2}$$

$$V_0 = V_P + \overline{P}$$

$$\overline{AB} = V_P + \overline{P}$$

$$\overline{AB} = V_P + \overline{P}$$

$$\overline{AD} + V_P + \overline{P}$$

$$\overline{AB} = AD + BC - \overline{AB}$$



Interference



Example

1) Diren:
$$N_p = 24T$$
, $N_g = 48T$, $P = 4\frac{1}{10}$, $0 = 25^{\circ}$
 $\Gamma_p = \frac{1}{2} \frac{N_p}{P} = \frac{1}{2} \frac{24}{4} = 3$ in, $\Gamma_g = \frac{1}{2} \cdot \frac{48}{4} = 6$ in
 $\Gamma_{a,p} = \Gamma_{p+q} = \Gamma_{p+p} = 3 + \frac{1}{4} = 3.25$ in, $\Gamma_{a,p} = 6 + \frac{1}{4} = 6.25$ in



$$\Gamma_{b,p} = \Gamma_{p} C_{ab} \phi = 3C_{ab} 2s^{\circ} = 2.72 \text{ in} \qquad \Gamma_{b,g} = 6C_{ab} 2s^{\circ} = 5.44 \text{ in}$$

$$AD = \int \Gamma_{a,p}^{2} - \Gamma_{b,p}^{2} = \sqrt{3.25^{2} - 2.72^{2}} = 1.78 \text{ in}$$

$$BC = \int \Gamma_{a,g}^{2} - \Gamma_{b,g}^{2} = \sqrt{6.25^{2} - 5.44^{2}} = 3.08 \text{ in}$$

$$AB = (\Gamma_{p} + \Gamma_{g}) D_{in} \phi = (3+6) S_{in} 2s^{\circ} = 3.80 \text{ in}$$

$$CR. = \frac{AD + BC - AB}{2\pi \Gamma_{b}/N} = \frac{1.78 + 3.08 - 3.80}{2\pi (2.72/24)} = 1.49 \text{ teeth}$$